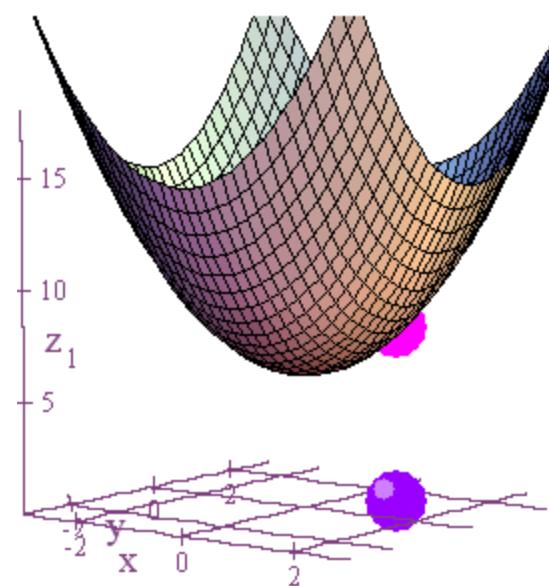


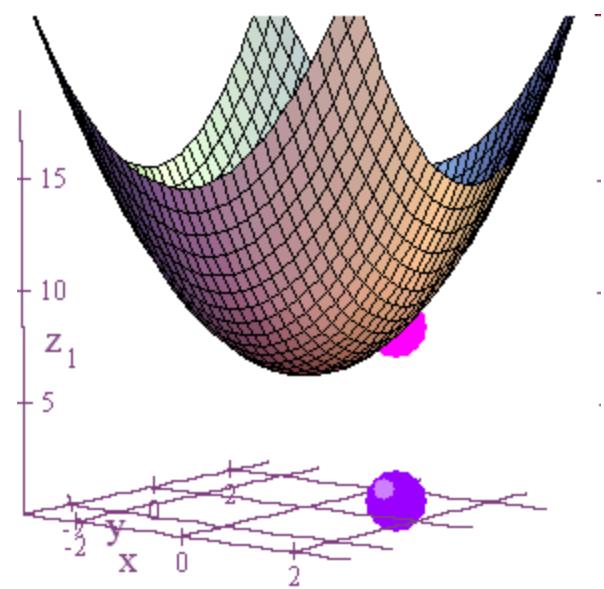
# REVIEW



$$z = x^2 + y^2 + 6$$

$$P = (1, 1, 8)$$

$$Q = (1, 1, 0)$$



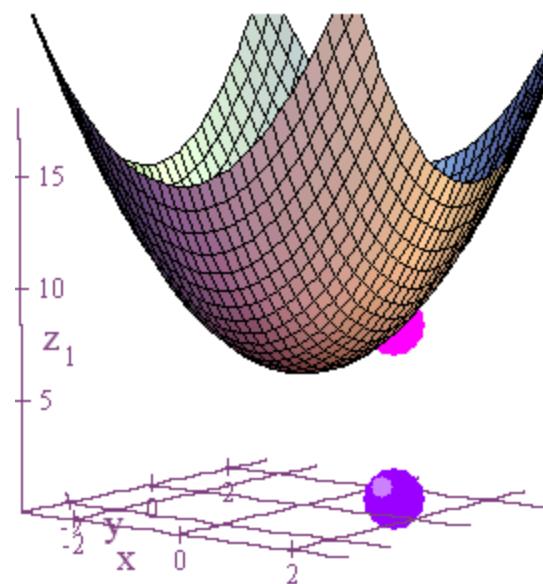
$$z = x^2 + y^2 + 6$$

$$\nabla z = \frac{\partial z}{\partial x} \hat{i} + \frac{\partial z}{\partial y} \hat{j} = 2x\hat{i} + 2y\hat{j}$$

$$P = (1, 1, 8)$$

$$\nabla z(1, 1) = 2\hat{i} + 2\hat{j}$$

$$Q = (1, 1, 0)$$



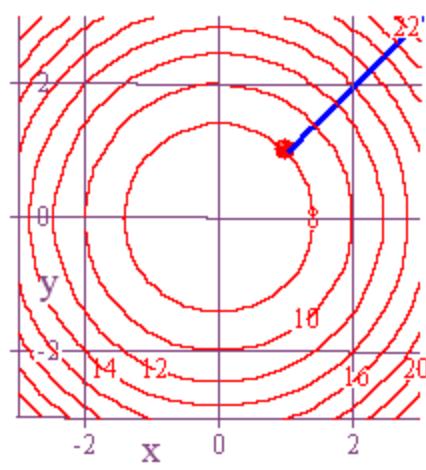
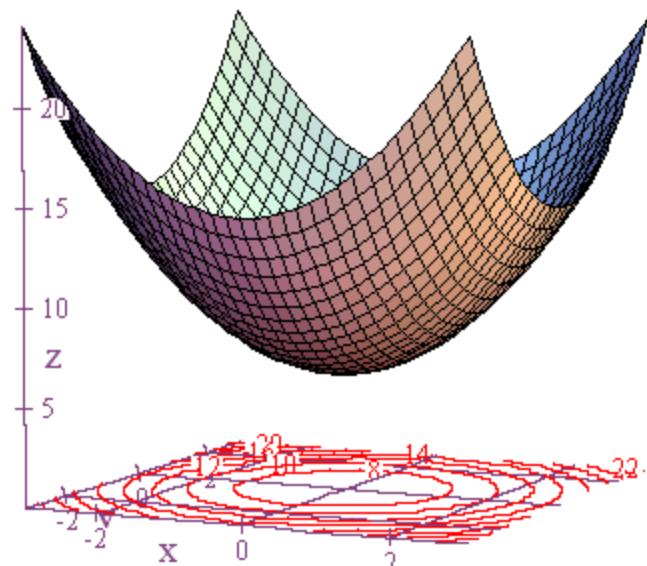
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$$\nabla z(1,1) = 2\hat{i} + 2\hat{j}$$



$$x = 1 + 2t$$

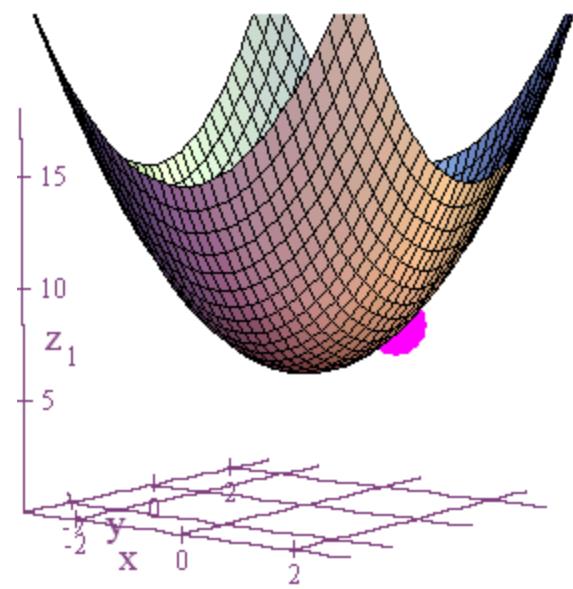
$$y = 1 + 2t$$

$$0 \leq t \leq 1$$

$$0 = x^2 + y^2 - z + 6$$

$$w = x^2 + y^2 - z + 6$$

$$P = (1, 1, 8)$$



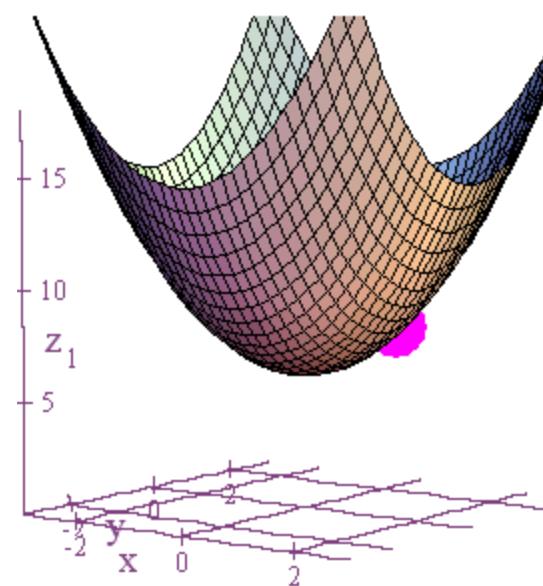
$$0 = x^2 + y^2 - z + 6$$

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$$\nabla w = \frac{\partial w}{\partial x} \hat{i} + \frac{\partial w}{\partial y} \hat{j} + \frac{\partial w}{\partial z} \hat{k} = 2x\hat{i} + 2y\hat{j} - \hat{k}$$

$$\nabla w(1, 1, 8) = 2\hat{i} + 2\hat{j} - \hat{k}$$



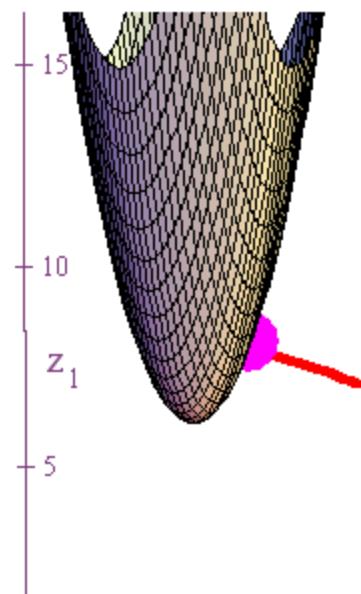
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$$\nabla w(1, 1, 8) = 2\hat{i} + 2\hat{j} - \hat{k}$$



$$x = 1 + 2t$$

$$y = 1 + 2t$$

$$z = 8 - t$$

$$0 \leq t \leq 1$$

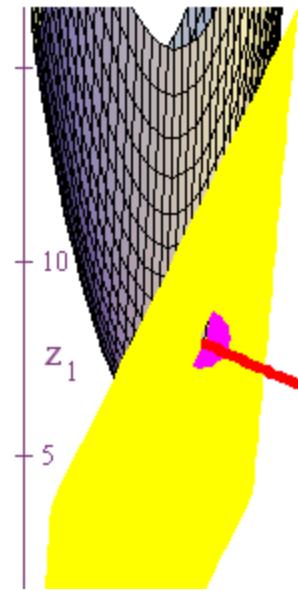
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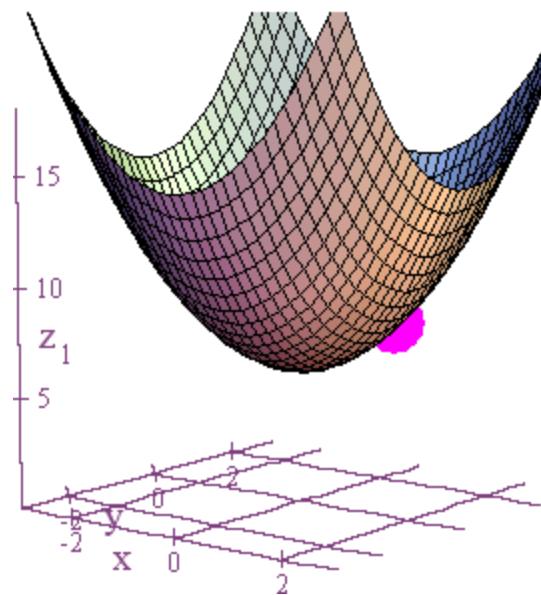
$$z = 2x + 2y + 4$$

$$\nabla z = \frac{\partial z}{\partial x} \hat{i} + \frac{\partial z}{\partial y} \hat{j} = 2x\hat{i} + 2y\hat{j}$$

$$z = f(x, y) = x^2 + y^2 + 6$$

$$P = (1, 1, 8)$$

$$\nabla z(1, 1) = 2\hat{i} + 2\hat{j}$$



$$\vec{u} = \frac{1}{\sqrt{2}}\hat{i} + \frac{1}{\sqrt{2}}\hat{j}$$

$$D_{\vec{u}} f = \nabla f \cdot \vec{u} = \frac{2x}{\sqrt{2}} + \frac{2y}{\sqrt{2}} = \sqrt{2}x + \sqrt{2}y$$

$$D_{\vec{u}} f(1, 1) = 2\sqrt{2}$$

$$z = f(x, y) = x^2 + y^2 + 6$$

Construct the tangent line.

$$P = (1, 1, 8)$$

$$\vec{v} = \hat{i} + \hat{j} + 8\hat{k}$$

$$\nabla z(1,1) = 2\hat{i} + 2\hat{j}$$

$$\vec{u} = \frac{1}{\sqrt{2}}\hat{i} + \frac{1}{\sqrt{2}}\hat{j}$$

$$t\vec{u} = t\left(\frac{1}{\sqrt{2}}\hat{i} + \frac{1}{\sqrt{2}}\hat{j}\right) = \frac{t}{\sqrt{2}}\hat{i} + \frac{t}{\sqrt{2}}\hat{j}$$

$$D_{\vec{u}}f(1,1) = 2\sqrt{2}$$

$$\vec{w} = 2\sqrt{2}t\hat{k}$$

$$\vec{r}(t) = \vec{v} + t\vec{u} + \vec{w} = \left(1 + \frac{t}{\sqrt{2}}\right)\hat{i} + \left(1 + \frac{t}{\sqrt{2}}\right)\hat{j} + \left(8 + 2\sqrt{2}t\right)\hat{k}$$

$$0 \leq t < \infty$$

$$0 = x^2 + y^2 - z + 6$$

$$w = x^2 + y^2 - z + 6$$

$$P = (1, 1, 8)$$

$$x = 1 + \frac{t}{\sqrt{2}}$$

$$y = 1 + \frac{t}{\sqrt{2}}$$

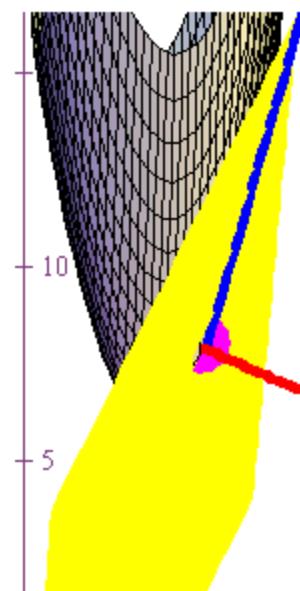
$$z = 8 + 2\sqrt{2}t$$

$$0 \leq t < \infty$$

$$z = 2x + 2y + 4$$

$$\nabla w = \frac{\partial w}{\partial x} \hat{i} + \frac{\partial w}{\partial y} \hat{j} + \frac{\partial w}{\partial z} \hat{k} = 2x\hat{i} + 2y\hat{j} - \hat{k}$$

$$\nabla w(1, 1, 8) = 2\hat{i} + 2\hat{j} - \hat{k}$$



$$x = 1 + 2t$$

$$y = 1 + 2t$$

$$z = 8 - t$$

$$0 \leq t \leq 1$$

Recall that:

$$D_{\vec{u}} f = \nabla f \bullet \vec{u} = \|\nabla f\| \|\vec{u}\| \cos \theta = \|\nabla f\| \cos \theta$$

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Consequently,

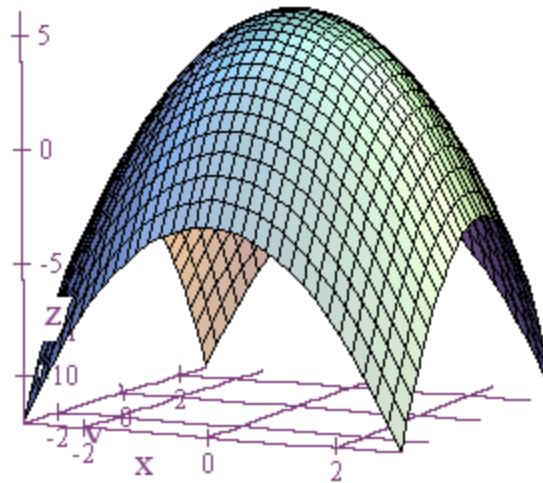
$D_{\vec{u}} f$  is maximized when  $\theta = 0$

$D_{\vec{u}} f$  is minimized when  $\theta = \pi$

$D_{\vec{u}} f = 0$  when  $\nabla f \perp \vec{u}$

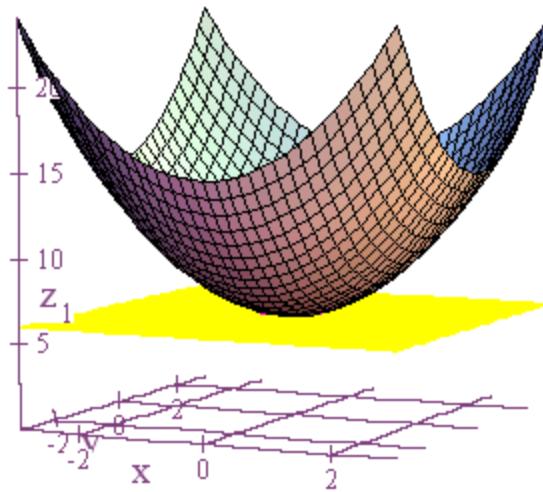
In other words:

1. You ascend a hill most rapidly when you go in the compass direction indicated by the gradient vector of  $z$ .
2. You descend a hill most rapidly when you go in the compass direction indicated by the negative of the gradient vector of  $z$ .
3. Your elevation doesn't change when you go in a compass direction at right angles to the gradient vector of  $z$ .



$$z = x^2 + y^2 + 6$$

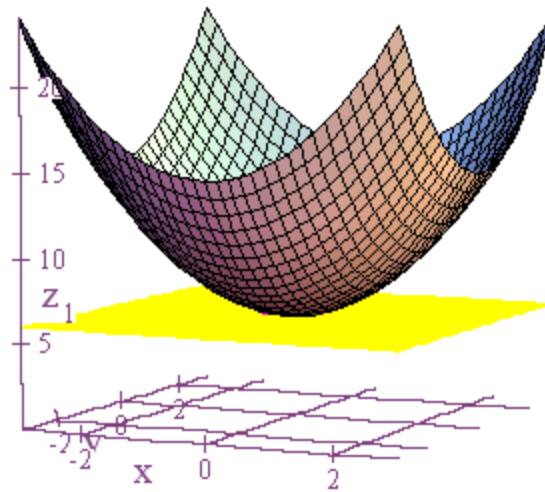
Recall that when at a relative maximum or minimum point on a surface, if a tangent plane exists, then it must be horizontal.



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Recall that when at a relative maximum or minimum point on a surface, if a tangent plane exists, then it must be horizontal.

This also suggests that the partial derivatives are zero at such a point.

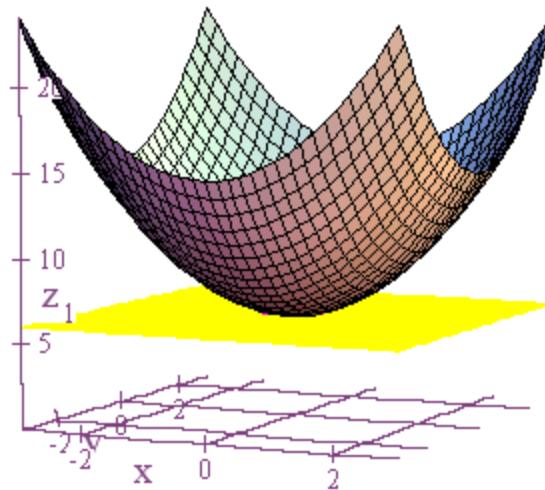


$$z = x^2 + y^2 + 6$$

Recall that when at a relative maximum or minimum point on a surface, if a tangent plane exists, then it must be horizontal.

This also suggests that the partial derivatives are zero at such a point.

And this leads to the following test.



**Definition:** Let  $(a,b)$  be a point contained in an open region  $R$  on which a function  $z = f(x, y)$  is defined. Then  $(a,b)$  is a **critical point** if any of the following conditions are true:

1.  $z_x(a,b) = 0 = z_y(a,b)$
2.  $z_x(a,b)$  does not exist
3.  $z_y(a,b)$  does not exist

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1.  $z_x(a,b) = 0 = z_y(a,b)$
2.  $z_x(a,b)$  does not exist
3.  $z_y(a,b)$  does not exist

**Theorem:** If  $z = f(x, y)$  has a local maximum or a local minimum at a point  $(a,b)$  contained within an open region  $R$  on which  $z = f(x, y)$  is defined, then  $(a,b)$  is a **critical point**.

**Second Partials Test:** Suppose  $z = f(x, y)$  has continuous second partial derivatives on an open region containing a point  $(a, b)$  such that

$z_x(a, b) = 0 = z_y(a, b)$ , and let

$$D = D(a, b) = \begin{vmatrix} z_{xx}(a, b) & z_{xy}(a, b) \\ z_{yx}(a, b) & z_{yy}(a, b) \end{vmatrix} = z_{xx}(a, b)z_{yy}(a, b) - z_{xy}(a, b)z_{yx}(a, b).$$

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Then:

1. If  $D > 0$  and  $z_{xx}(a, b) > 0$ ,  $f(a, b)$  is a **local minimum**.
2. If  $D > 0$  and  $z_{xx}(a, b) < 0$ ,  $f(a, b)$  is a **local maximum**.
3. If  $D < 0$ ,  $(a, b, f(a, b))$  is a **saddle point**.
4. If  $D = 0$ , the test is **inconclusive**.

Hence,

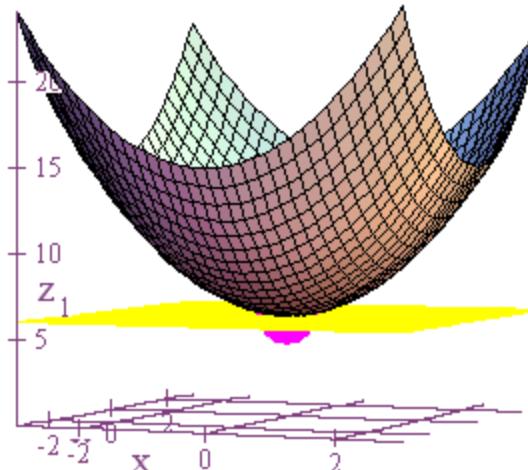
$$z = x^2 + y^2 + 6$$

$$z_x = 2x$$

$$z_y = 2y$$

$$\begin{aligned} z_x = 0 &\Rightarrow 2x = 0 \Rightarrow x = 0 \\ z_y = 0 &\Rightarrow 2y = 0 \Rightarrow y = 0 \Rightarrow \text{Critical Point} = (0, 0) \end{aligned}$$

$$D = \begin{vmatrix} z_{xx} & z_{xy} \\ z_{yx} & z_{yy} \end{vmatrix} = \begin{vmatrix} 2 & 0 \\ 0 & 2 \end{vmatrix} = 4$$



$$\begin{aligned} D(0,0) &= 4 > 0 \\ z_{xx}(0,0) &= 2 > 0 \Rightarrow (0,0,6) \text{ is a local minimum point} \end{aligned}$$